

COMPOSITION OF LORENTZ TRANSFORMATIONS

$U := \begin{bmatrix} 2 \\ \sqrt{2} \\ 1 \end{bmatrix}$ Find the Lorentz transformation into the rest frame of the observer with 4-velocity U . (It is understood that $U_z = 0$ and we ignore the z components of all vectors.)

$$\begin{matrix} 2 & 2 & 2 \\ -U & + U & + U \\ 0 & 1 & 2 \end{matrix} = -1 \quad \text{so this is indeed a normalized 4-velocity.}$$

Method 1: Find the Lorentz transformation that eliminates the y component; then the one that eliminates the x component.

$$\begin{matrix} U \\ 2 \\ U \\ 0 \end{matrix} \quad v_y := \frac{\quad}{\quad} \quad v_y = 0.5 \quad \text{gamy} := \frac{1}{\sqrt{1 - v_y^2}} \quad \text{gamy} = 1.155$$

$$L_y := \begin{bmatrix} \text{gamy} & 0 & -v_y \cdot \text{gamy} \\ 0 & 1 & 0 \\ -v_y \cdot \text{gamy} & 0 & \text{gamy} \end{bmatrix} \quad L_y \cdot U = \begin{bmatrix} 1.732 \\ 1.414 \\ 0 \end{bmatrix} \quad U_y := L_y \cdot U$$

$$\begin{matrix} U_y \\ 1 \\ U_y \\ 0 \end{matrix} \quad v_x := \frac{\quad}{\quad} \quad v_x = 0.816 \quad \text{gamx} := \frac{1}{\sqrt{1 - v_x^2}} \quad \text{gamx} = 1.732$$

$$L_x := \begin{bmatrix} \text{gamx} & -v_x \cdot \text{gamx} & 0 \\ -v_x \cdot \text{gamx} & \text{gamx} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad L_x \cdot U_y = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{as desired.}$$

$$L_1 := L_x \cdot L_y \quad L_1 = \begin{bmatrix} 2 & -1.414 & -1 \\ -1.633 & 1.732 & 0.816 \\ -0.577 & 0 & 1.155 \end{bmatrix} \quad L_1 \cdot U = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Method 2: Same as before, but treat x first.

$$\begin{matrix} U \\ 1 \\ U \\ 0 \end{matrix} \quad v_x := \frac{\quad}{\quad} \quad v_x = 0.707 \quad \text{gamx} := \frac{1}{\sqrt{1 - v_x^2}} \quad \text{gamx} = 1.414$$

$$L_x := \begin{bmatrix} \text{gamx} & -v_x \cdot \text{gamx} & 0 \\ -v_x \cdot \text{gamx} & \text{gamx} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad L_x \cdot U = \begin{bmatrix} 1.414 \\ 0 \\ 1 \end{bmatrix} \quad U_x := L_x \cdot U$$

$$v_y := \frac{U_x}{U_x^2} \quad v_y = 0.707 \quad \gamma_{vy} := \frac{1}{\sqrt{1 - v_y^2}} \quad \gamma_{vy} = 1.414$$

$$L_y := \begin{bmatrix} \gamma_{vy} & 0 & -v_y \cdot \gamma_{vy} \\ 0 & 1 & 0 \\ -v_y \cdot \gamma_{vy} & 0 & \gamma_{vy} \end{bmatrix} \quad L_y \cdot U_x = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{as desired.}$$

$$L_2 := L_y \cdot L_x \quad L_2 = \begin{bmatrix} 2 & -1.414 & 9 & -1 \\ -1 & 1.414 & 0 & 0 \\ -1.414 & 1 & 1.414 & 0 \end{bmatrix} \quad L_2 \cdot U = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Note that L_1 and L_2 are NOT equal, but both seem to transform into the rest frame of U .

$$L_1 \cdot L_2^{-1} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0.816 & 0.577 \\ 0 & -0.577 & 0.816 \end{bmatrix} \quad \text{The difference between them is a spatial rotation! This is an inherent ambiguity in "the rest frame of U".}$$

Method 3: Choose spatial axes so that the velocity is in the x direction. Solve that 1-dimensional problem, then rotate back.

$$\tanh\theta := \frac{U}{U^2} \quad \cosh\theta := \frac{1}{\sqrt{1 - \tanh^2\theta}}$$

$$\sinh^2\theta + \cosh^2\theta = 1$$

$$\sinh\theta = 0.577 \quad \cosh\theta = 0.816$$

$$R := \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cosh\theta & \sinh\theta \\ 0 & -\sinh\theta & \cosh\theta \end{bmatrix} \quad U_r := R \cdot U \quad U_r = \begin{bmatrix} 2 \\ 1.732 \\ 0 \end{bmatrix}$$

$$v_x := \frac{U_r}{U_r^2} \quad v_x = 0.866 \quad \gamma_{vx} := \frac{1}{\sqrt{1 - v_x^2}} \quad \gamma_{vx} = 2$$

$$L_r := \begin{bmatrix} \gamma_{vx} & -v_x \cdot \gamma_{vx} & 0 \\ -v_x \cdot \gamma_{vx} & \gamma_{vx} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad L_r \cdot U_r = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$L3 := R^{-1} \cdot Lr \cdot R \quad L3 = \begin{bmatrix} 2 & -1.414 & -1 \\ -1.414 & 1.667 & 0.471 \\ -1 & 0.471 & 1.333 \end{bmatrix} \quad L3 \cdot U = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$L3 \cdot L1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.962 & -0.272 \\ 0 & 0.272 & 0.962 \end{bmatrix} \quad L3 \cdot L2^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.943 & 0.333 \\ 0 & -0.333 & 0.943 \end{bmatrix}$$

Thus L3 leads to a frame with a spatial orientation intermediate between those of L1 and L2.

Method 4: Let's construct L3 by a more geometrical method.

$$U_{\text{spat}} := \begin{bmatrix} 0 \\ U \\ 1 \\ U \\ 2 \end{bmatrix} \quad N := \frac{U_{\text{spat}}}{\sqrt{\begin{bmatrix} 2 & 2 \\ U & U \\ 1 & 2 \end{bmatrix}}} \quad N = \begin{bmatrix} 0 \\ 0.816 \\ 0.577 \end{bmatrix}$$

N is the unit vector in the direction of motion. The Lorentz transformation must leave alone spatial components perpendicular to N, while it mixes the spatial component parallel to N with the time component.

$$P(V) := N \cdot (N \cdot V) \quad P(U) = \begin{bmatrix} 0 \\ 1.414 \\ 1 \end{bmatrix} \quad P(V) \text{ is the component of } V \text{ parallel to } N.$$

$$Pr := \begin{bmatrix} N \cdot N & N \cdot N & N \cdot N \\ 0 & 0 & 0 & 1 & 0 & 2 \\ N \cdot N & N \cdot N & N \cdot N \\ 1 & 0 & 1 & 1 & 1 & 2 \\ N \cdot N & N \cdot N & N \cdot N \\ 2 & 0 & 2 & 1 & 2 & 2 \end{bmatrix} \quad Pr = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0.667 & 0.471 \\ 0 & 0.471 & 0.333 \end{bmatrix}$$

Pr is the matrix of the linear map V -> P(V). Check this:

$$P \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad P \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0.667 \\ 0.471 \end{bmatrix} \quad P \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0.471 \\ 0.333 \end{bmatrix}$$

$$\text{identity}(3) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad Pr \cdot \text{identity}(3) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0.667 & 0.471 \\ 0 & 0.471 & 0.333 \end{bmatrix}$$

Now the desired Lorentz transformation, acting on V, must give
 time component $\gamma V_0 - \gamma \beta (N \cdot V)$,
 parallel component $\gamma P(V) - \gamma \beta V_0 N$,
 and perpendicular component $V_{\text{spatial}} - P(V)$.
 See Jackson, Classical Electrodynamics, Sec. 11.2, for these
 equations in better notation than the computer is capable of.

$$\gamma := \frac{U}{\sqrt{1 - \frac{U^2}{c^2}}}$$

$$\beta := \frac{U}{c}$$

$$\beta = 0.866$$

$$L4_1 := \begin{bmatrix} \gamma & -\gamma \beta \cdot N & -\gamma \beta \cdot N \\ -\gamma \beta \cdot N & 1 & 0 \\ -\gamma \beta \cdot N & 0 & 1 \end{bmatrix}$$

$$L4_2 := (\gamma - 1) \cdot Pr \qquad L4 := L4_1 + L4_2$$

Here we have used the fact that the matrix of $V \rightarrow V_{\text{spatial}}$ is

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$L4 = \begin{bmatrix} 2 & -1.414 & -1 \\ -1.414 & 1.667 & 0.471 \\ -1 & 0.471 & 1.333 \end{bmatrix} \qquad L3 = \begin{bmatrix} 2 & -1.414 & -1 \\ -1.414 & 1.667 & 0.471 \\ -1 & 0.471 & 1.333 \end{bmatrix}$$

As expected, they are equal.